

# TC1 - Exam 2020-2021 - 2 hours

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All documents are allowed. No phone, no computer. You **must** use formal notation and you **must** define all mathematical terms you use.

## 1 Course questions (20 points)

- (1 point) Why do we want the training problem to be a convex or concave optimization problem?
- (2 points) What important property of convex functions can impact the optimization algorithm? Why?
- (1 point) What does "support vector" refer to in Support Vector Machines?
- (2 point) Why are slack variables introduced in the constrained formulation of SVM? (you can use a picture to illustrate your explanation)
- (1 point) In the course and lab exercise, we assumed that there was a feature always equal to one so we don't have to explicitly introduce a bias term in our scoring function. However we could have an explicit bias term instead, i.e. a scoring function of the form  $s(\mathbf{x}) = \mathbf{x}^\top \mathbf{a} + b$ . Give a reason why we shouldn't apply regularization to the bias term when training a SVM (hint: think about the geometric interpretation of the binary SVM classifier).
- (2 points) Why is it interesting to optimize the dual formulation of a SVM via the coordinate ascent algorithm? (at least 2 reasons)
- (2 points) Let  $\mathbf{w} \in \mathbb{R}^k$  be a vector of scores and  $\hat{\mathbf{y}} \in \mathbb{R}^k$  be a one-hot vector representing the gold output. The negative log-likelihood loss for a softmax prediction function can be written as:

$$l(\hat{\mathbf{y}}, \mathbf{w}) = -\log(\hat{\mathbf{y}}^\top \text{softmax}(\mathbf{w}))$$

Compute the gradient  $\nabla_{\mathbf{w}} l(\hat{\mathbf{y}}, \mathbf{w})$ . How can it be interpreted?

- (3 points) We now consider the hinge loss:

$$h(\hat{\mathbf{y}}, \mathbf{w}) = \max(0, -\hat{\mathbf{y}}^\top \mathbf{w} + m + \max_{\mathbf{y} \in \mathcal{Y}(k) \setminus \{\hat{\mathbf{y}}\}} \mathbf{y}^\top \mathbf{w})$$

What is (one) sub-gradient  $\nabla_{\mathbf{w}} h(\hat{\mathbf{y}}, \mathbf{w})$ ? (We use the gradient notation just to simplify notation) How can it be interpreted? Compare with the gradient  $\nabla_{\mathbf{w}} l(\hat{\mathbf{y}}, \mathbf{w})$  of the previous function.

- (3 points) Computing the hinge loss function requires to solve an optimization problem over the set  $\mathbf{y} \in \mathcal{Y}(k) \setminus \{\hat{\mathbf{y}}\}$ . Propose and justify a definition of the hinge loss where this optimization is over  $\mathbf{y} \in \mathcal{Y}(k)$ , i.e. propose a formulation of the hinge loss of the form:

$$h(\hat{\mathbf{y}}, \mathbf{w}) = \max(0, \dots \max_{\mathbf{y} \in \mathcal{Y}(k)} \dots)$$

- (1 point) Why we shouldn't use the negative log-likelihood loss function when training a model based on the sparsemax prediction function?
- (2 points) Consider these three different loss functions for structured prediction: negative log-likelihood, SVM and SVM with rescaled margin. In which setting could you use each of these loss functions? Why?

## 2 Convex analysis (14 points)

- (2 points) What are two different interpretations of the subgradient of a convex function?
- (2 points) Let  $f(x) = -\log x$  be the negative logarithm function. Compute the Fenchel conjugate of the negative logarithm function. The Fenchel conjugate is defined as follows:

$$f^*(y) = \sup_x xy - f(x)$$

- (2 points)** Compute the Fenchel conjugate of the Fenchel conjugate of the negative logarithm function (i.e. the biconjugate of  $f(x)$ ). Is this result expected?
- (1 points)** If we consider the function  $h(x) = \log x$  instead, would we expect to have  $h^{**}(x) = h(x)$ ? Why? (no need to compute anything for this question)
- (2 points)** Explain how we can rely on Fenchel conjugates to define prediction functions (and prediction functions only) and why this is useful.
- (3 points)** Let  $f : X \rightarrow \mathbb{R}$  be a convex function where  $X \subset \mathbb{R}^n$  is a convex subset of  $\mathbb{R}^n$ . Prove that its extended-value extension  $\tilde{f} : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex.

$$\tilde{f}(x) = \begin{cases} f(x) & \text{if } x \in X \\ \infty & \text{otherwise} \end{cases}$$

- (2 points)** Why is it useful to rely on extended-value extension of functions? Why is it important that  $\tilde{f}(x)$  is convex? (you can give an example)

### 3 Fenchel-Young losses (16 points)

Note: You are expected to describe both the regularized prediction function  $q_\Omega$  and the associated Fenchel-Young loss  $L_\Omega$  in both questions.

- (8 points)** We assume the following scoring and prediction function for regression:

$$\begin{aligned} s(\mathbf{x}) &= \mathbf{a}^\top \mathbf{x} & s : \mathbb{R}^n &\rightarrow \mathbb{R} \\ q(w) &= w & q : \mathbb{R} &\rightarrow \mathbb{R} \end{aligned}$$

where  $\mathbf{a} \in \mathbb{R}^n$  are the parameters of the model. The standard training loss is the squared loss defined as  $l(\hat{y}, y) = \frac{1}{2} \|\hat{y} - y\|_2^2$  where  $\hat{y}$  is the gold output and  $y$  is the predicted output. Prove formally that we can express this prediction and loss function in the Fenchel-Young loss framework.

- (8 points)** We assume the following scoring and prediction for probabilistic binary classification:

$$\begin{aligned} s(\mathbf{x}) &= \mathbf{a}^\top \mathbf{x} & s : \mathbb{R}^n &\rightarrow \mathbb{R} \\ q(w) &= \sigma(w) & q : \mathbb{R} &\rightarrow ]0, 1[ \end{aligned}$$

where  $\sigma(w) = \frac{\exp(w)}{1 + \exp(w)}$  is the sigmoid function and  $\mathbf{a} \in \mathbb{R}^n$  are the parameters of the model. In other words, the function  $q$  returns the parameter  $\mu$  of a Bernoulli distribution defined as follows:

$$p(y; \mu) = \mu^y (1 - \mu)^{(1-y)}$$

The entropy of a Bernoulli distribution is defined as follows:

$$H[p(\cdot; \mu)] = -y \log y - (1 - y) \log(1 - y)$$

Build formally the regularized prediction function and the Fenchel-Young loss associated with this probabilistic binary classifier.

### Cheat sheet: KKT conditions

Assume we have a maximization problem defined as follows:

$$\begin{aligned} \max_{\mathbf{x}} \quad & f(\mathbf{x}) \\ \text{s.t.} \quad & g^{(i)}(\mathbf{x}) \geq 0 & \forall 1 \leq i \leq m \\ & h^{(i)}(\mathbf{x}) = 0 & \forall 1 \leq i \leq n \end{aligned}$$

where  $\mathbf{x} \in \mathbb{R}^k$ ,  $g^{(i)} \geq 0$  is a set of  $m$  inequality and  $h^{(i)}(\mathbf{x}) = 0$  is a set of  $n$  equality. An optimal solution  $\mathbf{x}^* \in \mathbb{R}^k$  of the mathematical program satisfies the following constraints:

(stationarity)	$\forall i : \frac{\partial}{\partial x_i} f(\mathbf{x}^*) + \sum_j \mu_j \frac{\partial}{\partial x_i} g^{(j)}(\mathbf{x}^*) - \sum_j \lambda_j \frac{\partial}{\partial x_i} h^{(j)}(\mathbf{x}^*) = 0$
(primal feasibility)	$\forall i : g^{(i)}(\mathbf{x}^*) \geq 0$
	$\forall i : h^{(i)}(\mathbf{x}^*) = 0$
(dual feasibility)	$\forall i : \mu_i \geq 0$
(complementary slackness)	$\sum_i \mu_i g^{(i)}(\mathbf{x}^*) \geq 0$

where  $\mu \in \mathbb{R}_+^m$  and  $\lambda \in \mathbb{R}^n$  are dual variables associated with primal inequalities and equalities, respectively.